

(19) World Intellectual Property
Organization
International Bureau



(43) International Publication Date
7 July 2005 (07.07.2005)

PCT

(10) International Publication Number
WO 2005/062275 A1

(51) International Patent Classification⁷: **G08G 1/052, 1/01** (74) Agent: **PHILLIPS ORMONDE & FITZPATRICK**, 367 Collins Street, Melbourne, Victoria 3000 (AU).

(21) International Application Number: **PCT/AU2004/001815**

(22) International Filing Date:
21 December 2004 (21.12.2004)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data: 24 December 2003 (24.12.2003) AU 2003907181

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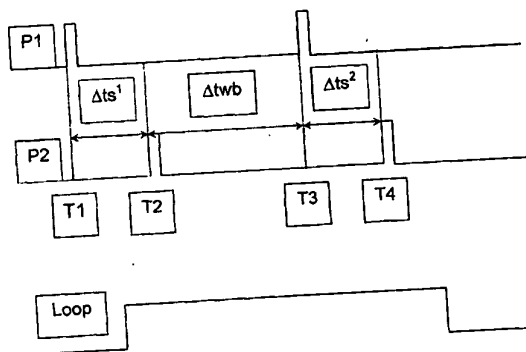
(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BW, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NA, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, CG, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, LT, LU, MC, NL, PL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Published:
— with international search report

(Continued on next page)

(54) Title: **VEHICLE SPEED DETERMINATION SYSTEM AND METHOD**



LEGEND

- P1 Piezoelectric Sensor 1
- P2 Piezoelectric Sensor 2
- Loop Inductive Loop
- T1 Time when Front Axle triggers P1
- T2 Time when Front Axle triggers P2
- T3 Time when Rear Axle triggers P1
- T4 Time when Rear Axle triggers P2
- Δts¹ Time Interval used to measure the Speed of the Front Axle (T2-T1)
- Δts² Time Interval used to measure the Speed of the Rear Axle (T4-T3)
- Δtwb Time Interval used to measure the Wheel Base (T3-T2)
- cs¹ Count Speed 1 is the Number of Interval Counts between T2 and T1 (Δts¹*freq)
- cs² Count Speed 2 is the Number of Interval Counts between T4 and T3 (Δts²*freq)
- cswb Count Speed Wheel Base is the Number of Interval Counts between T3 and T2 (Δtwb*freq)
- freq Reference Crystal Frequency
- d Distance separating P1 and P2

(57) Abstract: A method for verifying the speed of a vehicle having at least a front axle and a rear axle, using sensors separated by a distance. The presence of the vehicle is sensed and an image of the vehicle is recorded to enable the vehicle to be identified. The signals from sensors are triggered to emit signals which are received by the system to enable the speed of the vehicle to be determined. The signals are also used to determine a wheel base measurement for the vehicle. The determined wheel base measurement is compared to an actual wheel base measurement of the vehicle being sensed and any discrepancy between them is taken to be indicative of potential errors in the speed of the vehicle determined by the method. In one embodiment, the database is provided, the database containing data relating to various vehicle types associated with vehicle specifications including a validated wheel base measurement for each vehicle type.

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